

OwnTech TWIST Board Non-Isolated Dual Channel Reprogrammable Converter

The TWIST Board is a reprogrammable, bi-directional 300W power converter. It features a dual 12V to 72V low side and a single 10V to 110V high side. Its maximum current value is 8A per power channel.

The power channels can be used independently, yielding two output voltages or combined to double the current capacity.

The **TWIST Board** is fully open-source, compatible with either the SPIN board or any other programming system. It can communicate via CAN-bus or RS-485.

SPECIAL FEATURES

- 2 phase design
- DUAL or SINGLE power channel configuration
- Up to 97% Efficiency
- Standard size: 100mmx160mmx35mm
- Wide voltage operating range
- DC or AC operation
- Can be connected in parallel for higher power

- CAN bus communication compatible
- RS485 communication bus compatible
- Fully open-source
- Voltage and current mode libraries available
- Gitlab source here

AT A GLANCE

Rated Power

300W per module

Number of channels

Dual low side Single high side

Current ratings

8A per channel 16A in parallel

Voltage ratings

12V to 72V low side 12V to 100V high side



Figure 1 - TWIST converter pinout





I. General Power Block specifications

| PARAMETER | TEST CONDITIONS | MIN | ТҮР | MAX | UNIT |
|---------------------------------------|-----------------------------|-----|---------------------|-----|-----------------|
| ABSOLUTE MAXIMUM RATINGS | | | | | |
| Low-Side voltage | | | | 90 | V _{DC} |
| High-Side voltage | | 8 | | 120 | V _{DC} |
| Low-Side peak current per channel | | | | 8 | А |
| Power Output | | | | 300 | W |
| LC | OW-SIDE RATINGS | | | | |
| Number of power channels | | | 2 | | |
| Voltage range | | 12 | | 72 | V _{DC} |
| Max low-side peak current per channel | | | | 8 | А |
| Voltage ripple | | | 0.3 | | V _{DC} |
| н | GH-SIDE RATINGS | | | | |
| Number of power channels | | | 1 | | |
| Voltage range | | 12 | | 100 | V _{DC} |
| Voltage ripple | | | 0.3 | | V _{DC} |
| SWITCHING CHARACTERISTICS | | | | | |
| Switching frequency | | | 200 | | kHz |
| Selectable Deadtime | set resistors : $20k\Omega$ | | 200 | | ns |
| Maximum gate current | | | 4 | | А |
| TEMPERA | TURE AND DIMMENSION | IS | | | |
| Operating temperature | | -20 | | +60 | °C |
| Cooling principle | | Nat | ural convectio | n | |
| Dimensions | | | L100 W100 H35 | | mm |
| PRO | TECTION FEATURES | | | | |
| High side fuse | Tamb = 25°C | | 8 | | А |
| Low side fuse | Tamb = 25°C | | 8 | | А |



II. Communication specifications

| PARAMETER | TEST CONDITIONS | MIN | ТҮР | МАХ | UNIT |
|-----------|------------------|-----|--------|-----|--------|
| | CAN-FD | | | | |
| Baudrate | | | 500 | 500 | kBauds |
| Н | alf Duplex RS485 | | | | |
| Baudrate | | | 10 | 20 | MBauds |
| SPI | | | | | |
| Baudrate | | | 0.5 | 20 | MBauds |
| USART | | | | | |
| Baudrate | | | 115200 | | Bauds |

III. Synchronization



Figure 2. PWM synchronization between two boards, a server and a client.

Test with 2 boards connected with a 15cm RJ45 cable, measure taken with a 500Mhz bandwidth oscilloscope.

| PARAMETER | SYMBOL | MIN | ТҮР | MAX | UNIT |
|---|--------|-----|------|-----|-------|
| PWM slewrate | | | 660 | | mV/ns |
| Delay between server PWM, and synchronized client PWM | td | | 24.2 | | ns |
| Jitter of PWM client | tj | | 4.8 | | ns |

IV. Analog communication



Figure 3. Step response of the analog communication



Test made with 2 boards (a server and a client), connected with a 15cm RJ45 cable. The server board is sending a 16 bit value equal to 2000 via the analog communication.

The step response is measured with a 500Mhz bandwidth oscilloscope.

| PARAMETER | SYMBOL | MIN | ТҮР | МАХ | UNIT | |
|---|--|-----|---------|-----|------|--|
| Step respons | Step response from 1V to 1.25V analysis | | | | | |
| Time to reach and stay at $\pm 5\%$ of the steady-state value | Δt5% | | 1.7 | | μs | |
| Steady-state value | Vfinal | | 1.25 | | V | |
| ±5% Steady-state value interval | ∆V = 0.1*Vfinal | | 0.125 | | V | |
| Bandwidth | $f_c = \frac{3}{2 * \pi * \Delta t_{5\%}}$ | | 281 | | kHz | |
| Statistical distribution of 10235 data samples received by the client board when server sends a 16bit value of 2000 | | | | | 000 | |
| Approximate normal distribution mean | μ | | 2032.65 | | | |
| Approximate normal distribution variance | 0 ² | | 0.795 | | | |

V.1 Indication of where analog measures are made on the board



V.2 Measurement chain

OwnTech's TWIST Board implements full observability on all low-side and high-side power channels through isolated measurements.

| | V _{Low1} | | | |
|---------------------------------|-------------------------|--|-----|--|
| Sensor technology | | Voltage divider and isolation amplifier | | |
| Bandwidth | | 60 | kHz | |
| Signal side amplitude | | ±250 | mV | |
| Full scale range | | ±80 | V | |
| | V _{Low2} | • | | |
| Sensor technology | | Voltage divider and isolation amplifier | | |
| Bandwidth | | 60 | kHz | |
| Signal side amplitude | | ±250 | mV | |
| Full scale range | | ±80 | V | |
| | V _{High} | | | |
| Sensor technology | | Voltage divider and isolation amplifier | | |
| Bandwidth | | 100 | kHz | |
| Signal side amplitude | | +2 | V | |
| Full scale range | | 120 | V | |
| | Low1 | | | |
| Sensor technology | | Isolated Hall effect sensor | | |
| Bandwidth | | 1000 | kHz | |
| Signal side amplitude | | ±20 | А | |
| Full scale range | | ±10 | А | |
| | I _{Low2} | | | |
| Sensor technology | | Isolated Hall effect sensor | | |
| Bandwidth | | 1000 | kHz | |
| Signal side amplitude | | ±20 | А | |
| Full scale range | | ±10 | А | |
| | I _{High} | | | |
| Sensor technology | | Isolated Hall effect sensor | | |
| Bandwidth | | 1000 | kHz | |
| Signal side amplitude | | ±20 | А | |
| Full scale range | | ±20 | A | |
| Heats | sink temperature sensor | | | |
| Sensor technology | | Thermistor | | |
| Full scale range | | -40 +110 | °C | |
| EMBEDDED ADC | | | | |
| ADC Technology | | Successive approximation (SAR) | | |
| Independant ADC peripherals | | 2 | - | |
| Number of channels per ADC | | 1 3 6 | | |
| Sampling time | | 530 | ns | |
| ADC trigger | | Programmable trigger instant on PWM period | | |
| Trigger event typical frequency | | 200 | kHz | |



IV.2 Relative accuracy of voltage and current measure

Trigger value = 6%, carrier mode = center aligned unless specified



7

V.1 Standard deviation on voltage and current specifications

Trigger value = 6%, carrier mode = center aligned unless otherwise noted

| PARAMETER | TEST CONDITIONS | MIN TYP MAX | UNIT |
|-------------------------|---------------------------|-------------|------|
| V _{ILOW1} STAN | NDARD DEVIATION MEAS | SURE | · |
| | Not averaged | 85 | mV |
| | Average of 2 measures | 61 | mV |
| | Average of 3 | 50 | mV |
| | Average of 5 | | |
| | measures | 39 | mv |
| | measures | 28 | mV |
| VILOW2 STAN | DARD DEVIATION MEAS | SURE | |
| | Not averaged | 82 | mV |
| | Average of 2 measures | 58 | mV |
| | Average of 3 measures | 47 | mV |
| | Average of 5 measures | 37 | mV |
| | Average of 10 measures | 27 | mV |
| V _{IHigh} STAN | DARD DEVIATION MEAS | | |
| | Not ave aged | 150 | mV |
| | A teres or 2 minasures | 108 | mV |
| _ | Average of 3 measures | 88 | mV |
| | measures | 68 | mV |
| | Average of 10 measures | 48 | mV |
| | DARD DEVIATION MEAS | SURE | 1 |
| | Not averaged | 34 | mA |
| | Average of 2 | 24 | mA |
| | Average of 3 measures | 20 | mA |
| | Average of 5 measures | 16 | mA |
| | Average of 10 | 11 | mA |
| III.0W2 STAN | | SURE | 1 |
| | Not averaged | 34 | mA |
| | Average of 2 | 24 | mA |
| | Average of 3 | 20 | mA |
| | measures Average of 5 | | |
| | measures | 15 | MA |
| | measures | 11 | mA |
| I _{IHigh} STAN | DARD DEVIATION MEAS | SURE | 1 |
| | Not averaged | 14 | mA |
| | Average of 2 measures | 10 | mA |
| | Average of 3 measures | 8 | mA |
| | Average of 5 measures | 6 | mA |
| | Average of 10 measures | 4 | mA |

TWIST Board Datasheet - rev 1

V.3 Theoretical calibration coefficients – results in Volts and Ampere

| Coefficient | Value |
|--------------|----------|
| Gain VLow1 | 0,045 |
| Offset VLow1 | -94,364 |
| Gain VLow2 | 0,045 |
| Offset VLow2 | -94,364 |
| Gain VHigh | 0,029964 |
| Offset VHigh | 0 |
| Gain ILow1 | 0,005 |
| Offset ILow1 | -10 |
| Gain ILow2 | 0,005 |
| Offset ILow2 | -10 |
| Gain IHigh | 0,005 |
| Offset IHigh | -10 |

V.4 Theoretical calibration coefficients – results in mili Volts and milli Ampere

| | Coefficient | Value |
|---|---------------|--------|
| | Gain VLow1 | 45,021 |
| | Offset VLow1 | -94364 |
| | Gain VLow2 | 45,021 |
| | Offset VLC 2 | -94364 |
| | Gain VHigh | 29,964 |
| | Officet VHigh | 0 |
| | Cain Low1 | 5 |
| | Offset ILow1 | -10000 |
| | Gain ILow2 | 5 |
| (| Offset ILow2 | -10000 |
| Y | Gain IHigh | 5 |
| | Offset IHigh | -10000 |



VI. Typical applications

OwnTech's TWIST has a series of modes of operation shown in the table below.

| MODE NAME | HIGH SIDE | LOW SIDE | Electrolytic capacitor | TYPICAL APPLICATION | FIGURE |
|-------------------------------|-----------|----------|---------------------------|--|--------|
| DC-DC Buck | Input | Output | ON | Battery charger | I |
| DC-DC Boost | Output | Input | ON | Fuel-cell converter | П |
| 1phase DC-AC Buck inverter | Input | Output | OFF | AC micro-grids | Ш |
| 3phase DC-AC Buck inverter | Input | Output | OFF | Permanent magnet low- voltage motor | IV |

VI. 1 Interleaved DCDC modes



Figure I - TWIST converter in Buck Mode



Figure II - TWIST converter in Boost Mode







DC-AC modes



Figure III - TWIST converter in single phase unipolar inverter mode



Figure III - TWIST converter in single phase bipolar inverter mode

VII. Mechanical specification





TWIST Board Datasheet - rev 1

VII. Revision history

| Date | Revision | Changes |
|--------------|----------|-----------------|
| 01-Janv-2024 | 1 | Initial release |